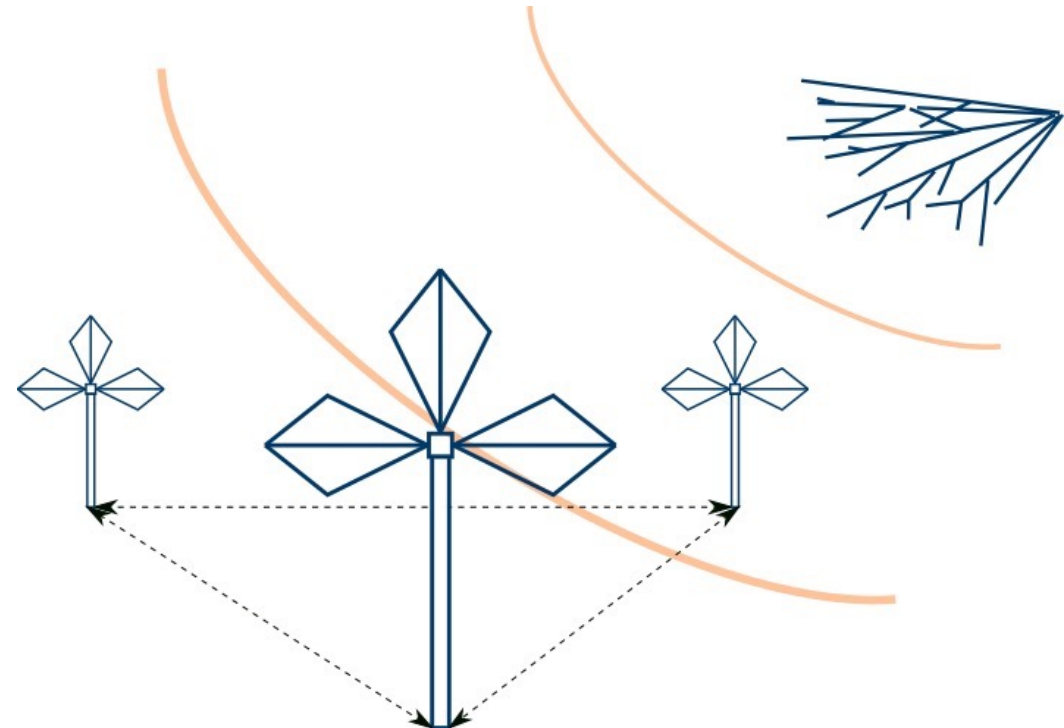




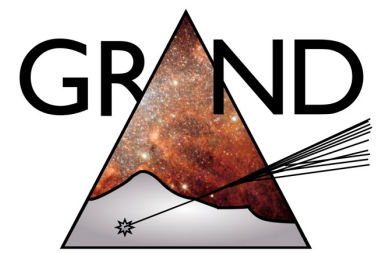
CHICAGO 2024



# Development of an Autonomous Detection-Unit Self-Trigger for GRAND

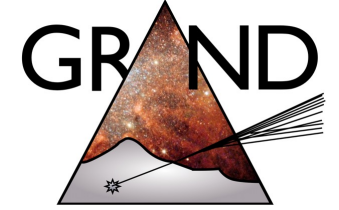
**Pablo Correa**  
for the GRAND collaboration

10<sup>th</sup> ARENA Workshop | 14 June 2024



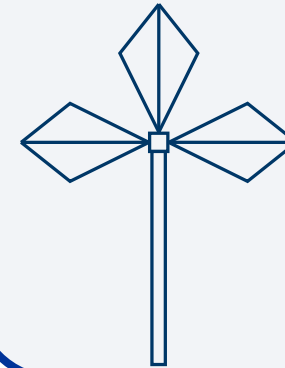
# The NUTRIG Project

GRAND overview:  
[Kumiko Kotera's talk](#)



- ▶ GRAND requires **autonomous radio trigger**
  - ▶ Maximum **purity**
  - ▶ Maximum signal selection **efficiency**
  - ▶ Minimum **SNR threshold**
- ▶ Trigger must be **scalable** to GRAND10k arrays
  - ▶ Minimum **cost**
  - ▶ Minimum **data bandwidth**
- ▶ **NUTRIG**: Develop scalable radio trigger
  - ▶ **First level trigger (FLT)**: **this talk**
  - ▶ **Second level trigger (SLT)**: [Jelena Köhler's talk](#)
  - ▶ **Air-shower emission model**: [Lukas Külzow's talk](#)

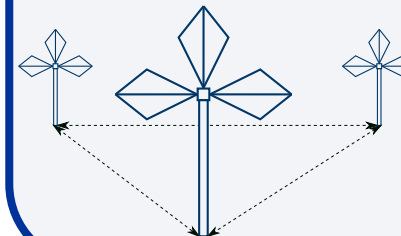
## Single detection unit (DU) trigger rate



GP300 nominal:  
1 kHz

**NUTRIG FLT target:  
100 Hz**

## Array of DUs trigger rate



GP300 nominal:  
10 Hz

**NUTRIG SLT target:  
1 Hz**

# GRAND Trigger Scheme



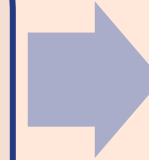
L1  
**FLT-0  
on FPGA**  
Threshold trigger on  
trace/wavelet

1 kHz



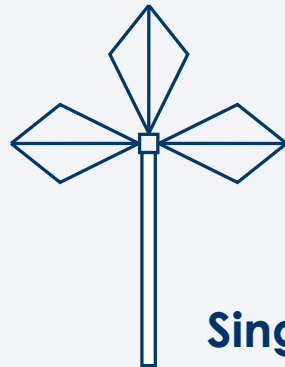
L2  
**FLT-1  
on CPU**  
Template fitting  
vs CNN

100 Hz



L3  
**SLT  
on central DAQ**  
Crude reconstruction  
with FLT-1 data

Currently on hardware



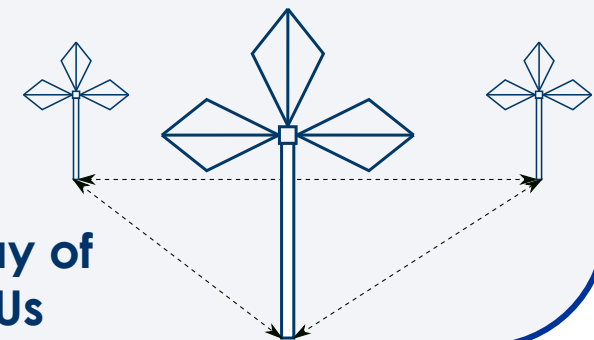
Single DU

**NUTRIG project**

**This talk**

Sandra Le Coz,  
Jean-Marc Colley, PC

**Jelena Köhler's talk**

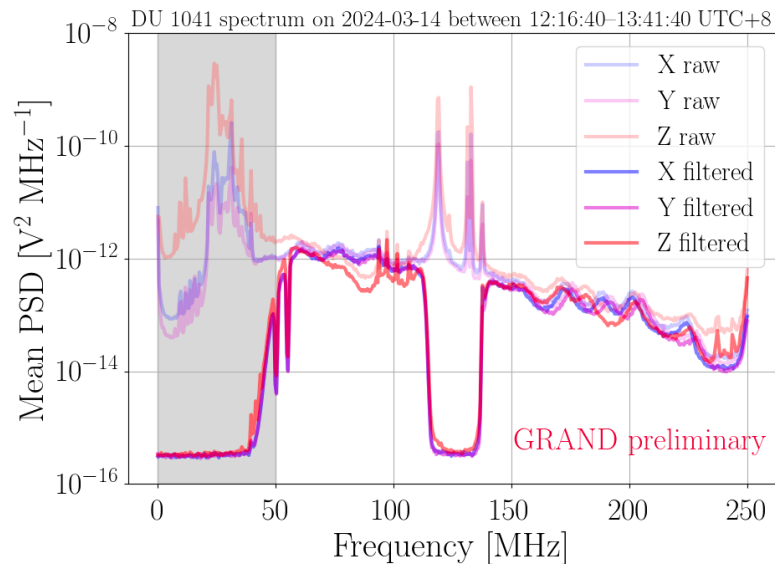


Array of  
DUs

# Offline FLT-1 Database: Background

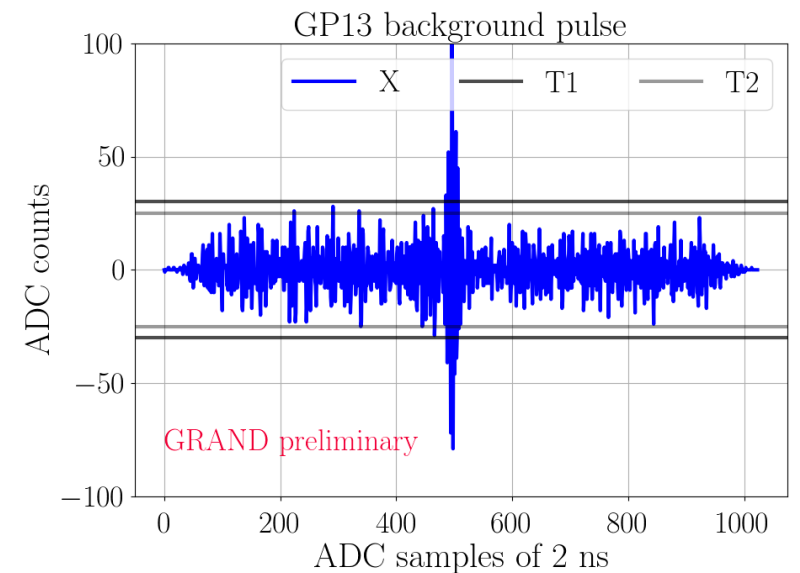
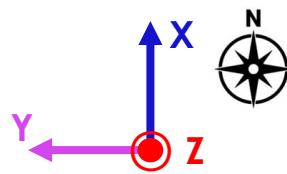


- ▶ **GRANDProto13** minimum-bias data
  - ▶ **Period:** 16 January 2024 – 24 April 2024
  - ▶ Traces of  $\sim 2 \mu\text{s}$  recorded **every 10 seconds**
- ▶ Offline **digital filters**
  - ▶ **Shortwaves:**  $< 50 \text{ MHz}$
  - ▶ **Aeronautic communications:**  $113.5\text{--}139.5 \text{ MHz}$
- ▶ Offline **double-threshold** FLT-0
  - ▶ **Similar** to current trigger on hardware
  - ▶ Only applied on **channels X & Y**
  - ▶ First T1 crossing is **FLT-0 trigger time  $t_0$**
  - ▶ T1 & T2 **not representative** of GP300 trigger rate!

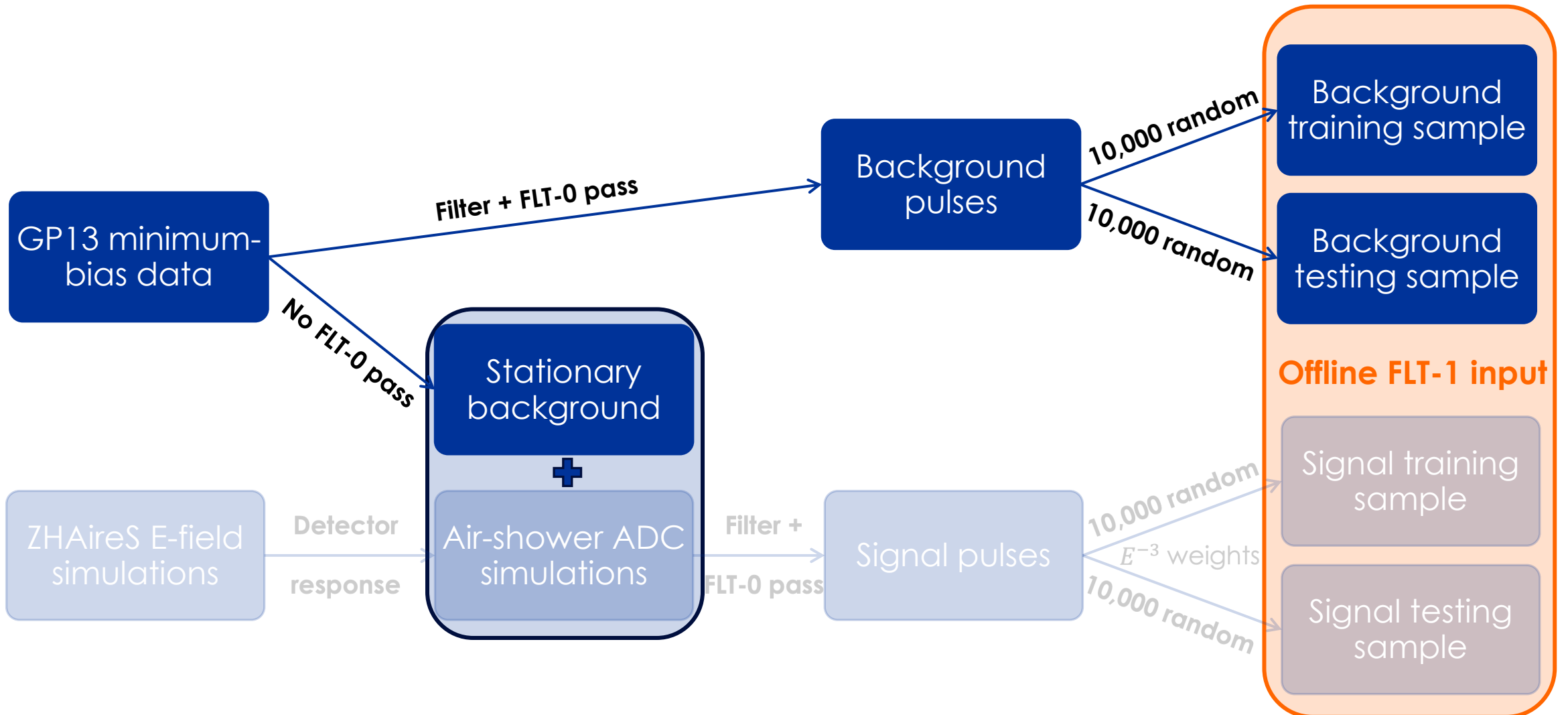


**GP300 details:**  
[Simon Chiche's talk](#)

**14-bit ADC @ 500 Msps**  
1 ADC count =  $109.86 \mu\text{V}$   
1 ADC sample =  $2 \text{ ns}$



# Offline FLT-1 Database Construction

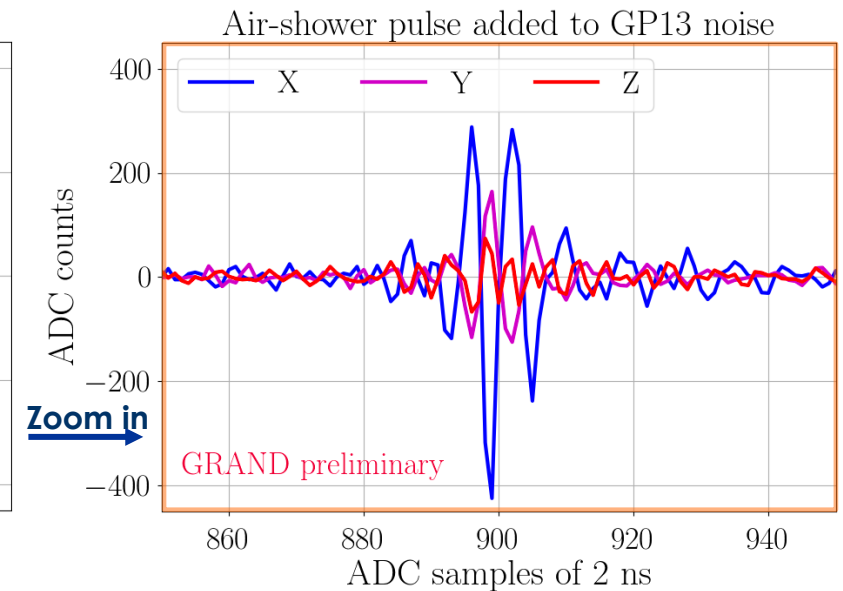
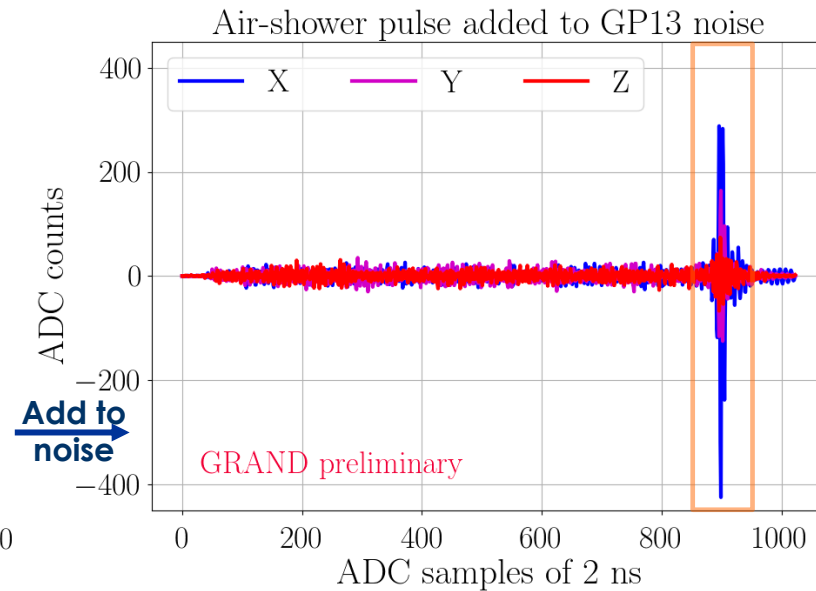
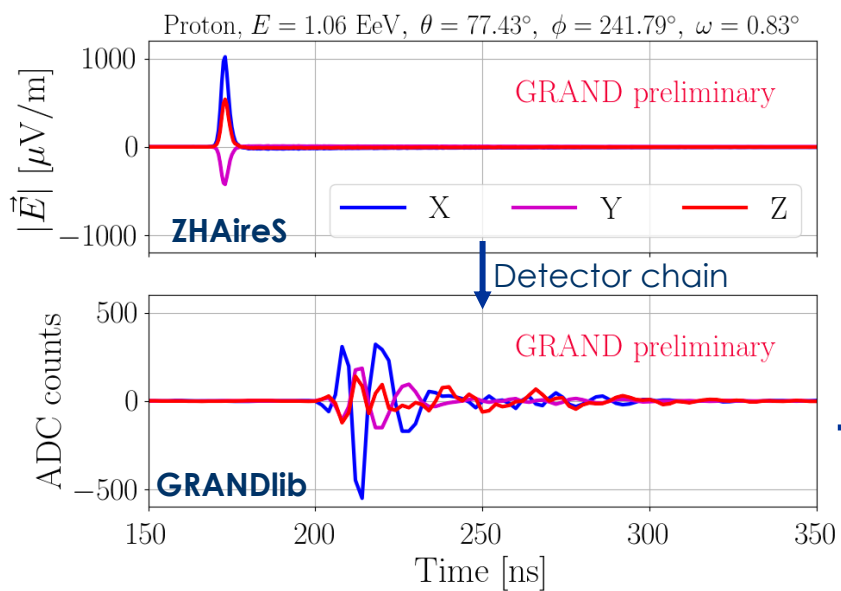


# Offline FLT-1 Database: Signal

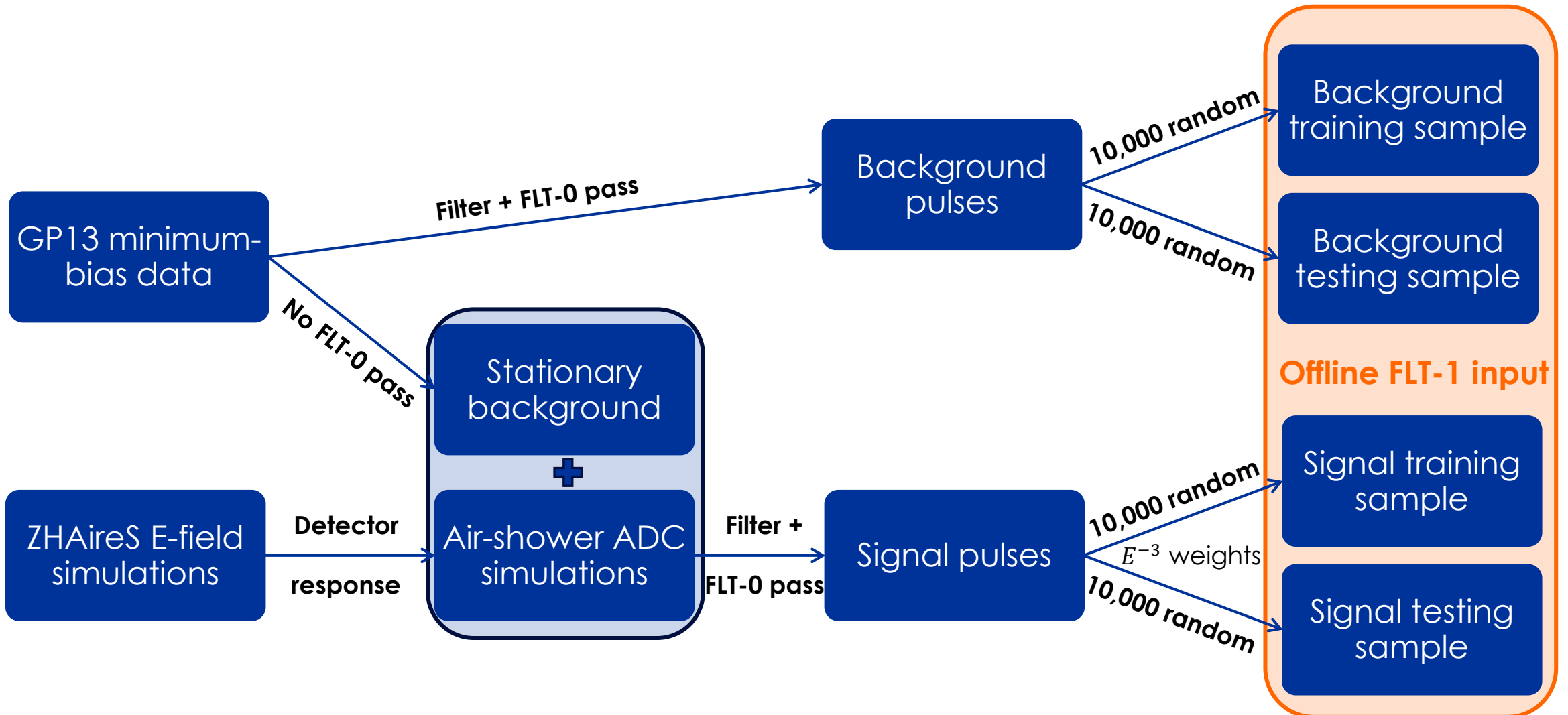


- ▶ 12,500 **ZHAireS** E-field simulations
- ▶ Process E-fields with **GRANDlib**
  - ▶ Realistic simulation of **GRAND detector pipeline**
  - ▶ Antenna response + RF chain **up to ADC**
- ▶ **Add to stationary noise** from GP13 data
  - ▶ **Apply digital filters** after adding signal to noise

**ZHAireS simulations**  
Proton primary  
 $\log_{10}(E/\text{eV}) \in [16.5, 18.5]$   
 $\theta \in [30.6^\circ, 87.3^\circ], \phi \in [0^\circ, 360^\circ]$



# Offline FLT-1 Database Construction



# FLT-1: Template Fitting

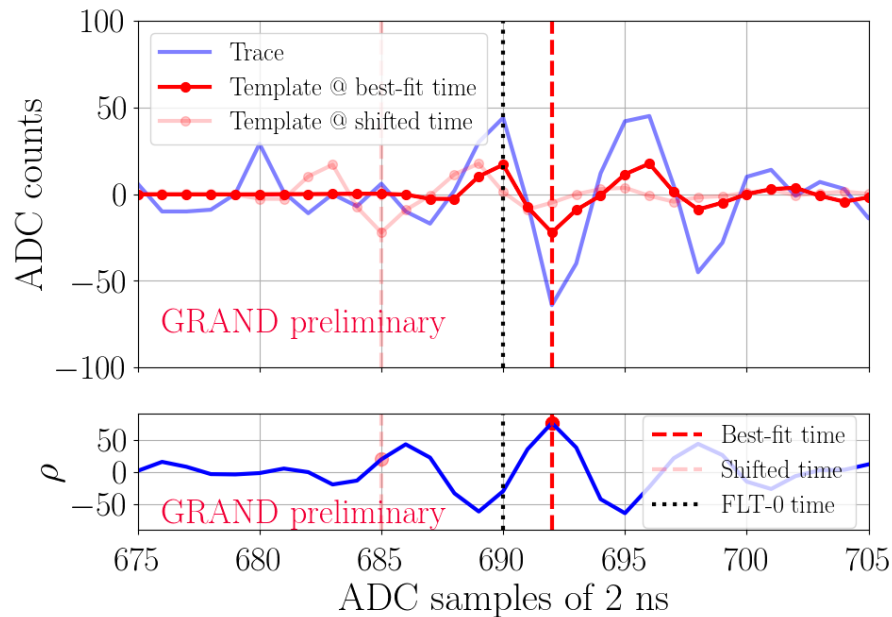
Template library (X+Y)  
ZHAireS + GRANDlib simulations  
Sampled for different  $\theta$  and  $\omega$



- ▶ Step 1: **Fit pulse-peak time**  $t_p$ 
  - ▶ **Maximum correlation** between trace  $V$  and template  $T$  [Henrichs+ PoS ICRC2023 259]

$$\rho(\tau) = \int T(t) V(t + \tau) dt$$

$$\hat{t}_p = \operatorname{argmax}_{\tau} |\rho(\tau)|$$



- ▶ Step 2: **Fit amplitude**  $\kappa$ 
  - ▶ **Least-squares fit** of template amplitude to trace

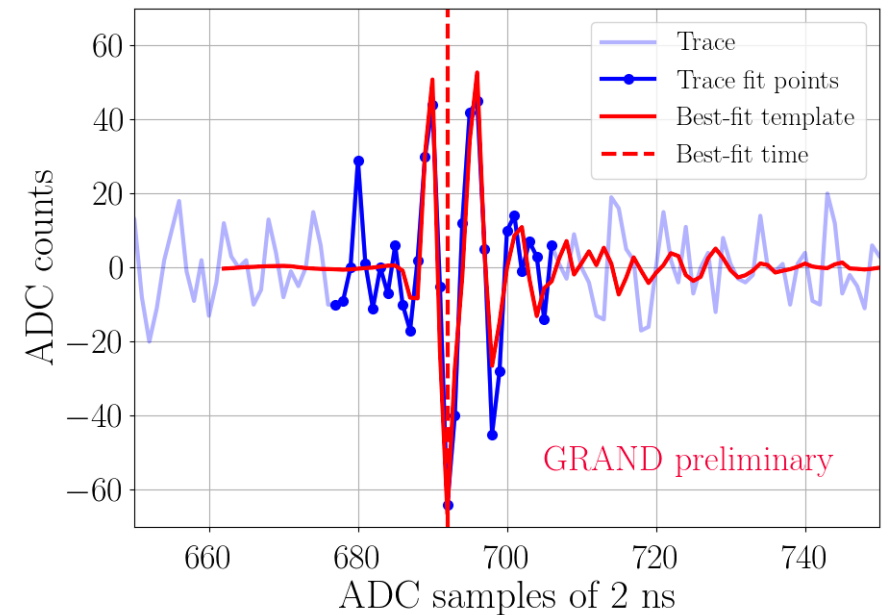
$$\chi_T^2 = \sum_i |V(t_i) - \kappa T(t_i)|^2 / \sigma_i^2, \quad \sigma_i = \text{RMS}^2 / V(t_i)$$

$$\hat{\kappa} = \operatorname{argmin}_{\kappa} \chi_T^2$$

**Repeat** steps 1 & 2 for 96 templates

Find **best-fit template**  
 $T_b = \operatorname{argmin}_T \chi_T^2$

Compute **test statistic**  
 $\text{TS} = \log_{10} |\hat{\kappa} \rho(\hat{t}_p)|$





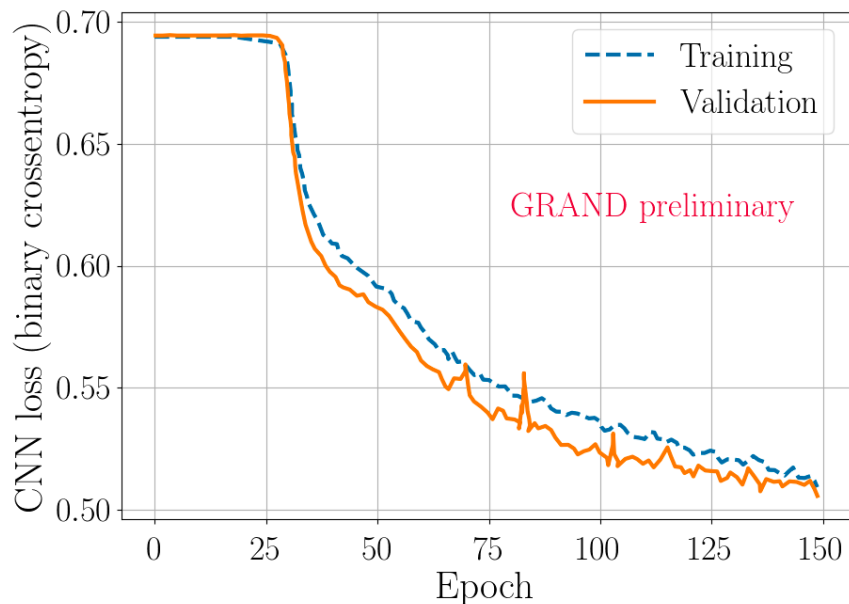
# FLT-1: Neural Network

**Developers**  
Sandra Le Coz (LPNHE)  
Jean-Marc Colley (LPNHE)

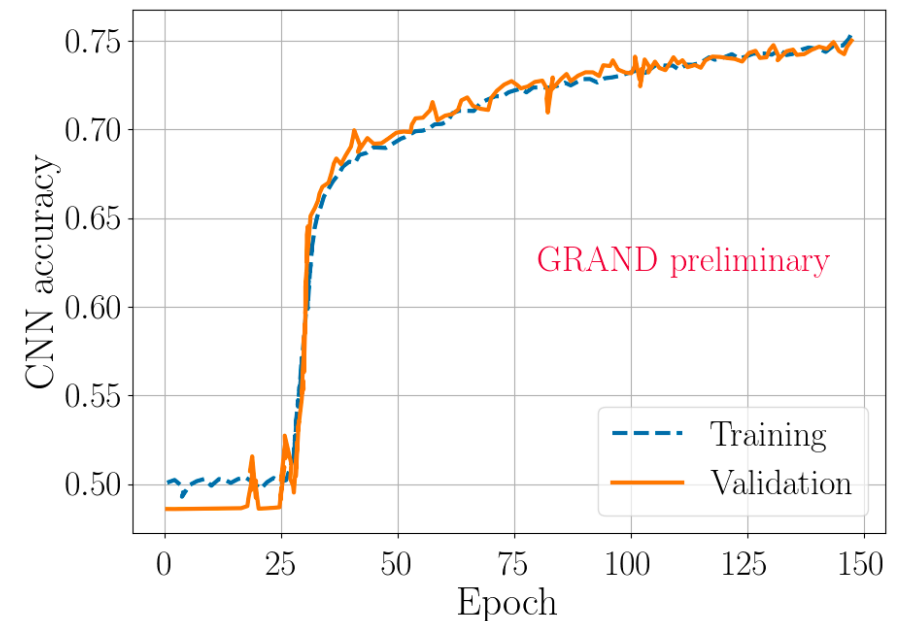


- ▶ **Convolutional neural network** (CNN)
  - ▶ Keras/**Tensorflow** framework (Lite for online)
  - ▶ **2 convolution layers** (3 @ ICRC 2023)  
[Le Coz PoS ICRC2023 224]
- ▶ **Training** sample: 2 x 10,000 traces (S+B)
- ▶ **Validation** subsample: 10% of training sample

- ▶ Minimization of **loss function**
- ▶ **Gradient descent** over 150 epochs
- ▶ **Accuracy** of CNN
  - ▶ Proportion of **well-classified traces**
    - ▶ **Background** classification: score < 0.5
    - ▶ **Signal** classification: score > 0.5



**CNN**  
**Input:** trace (X+Y+Z)  
  
Filters per layer: 32  
Kernel size: 11  
Padding: "same"  
Max-pooling: 4  
Dropout: 0.3  
Weights: ~14,000  
  
**Output:** score  $\in [0, 1]$

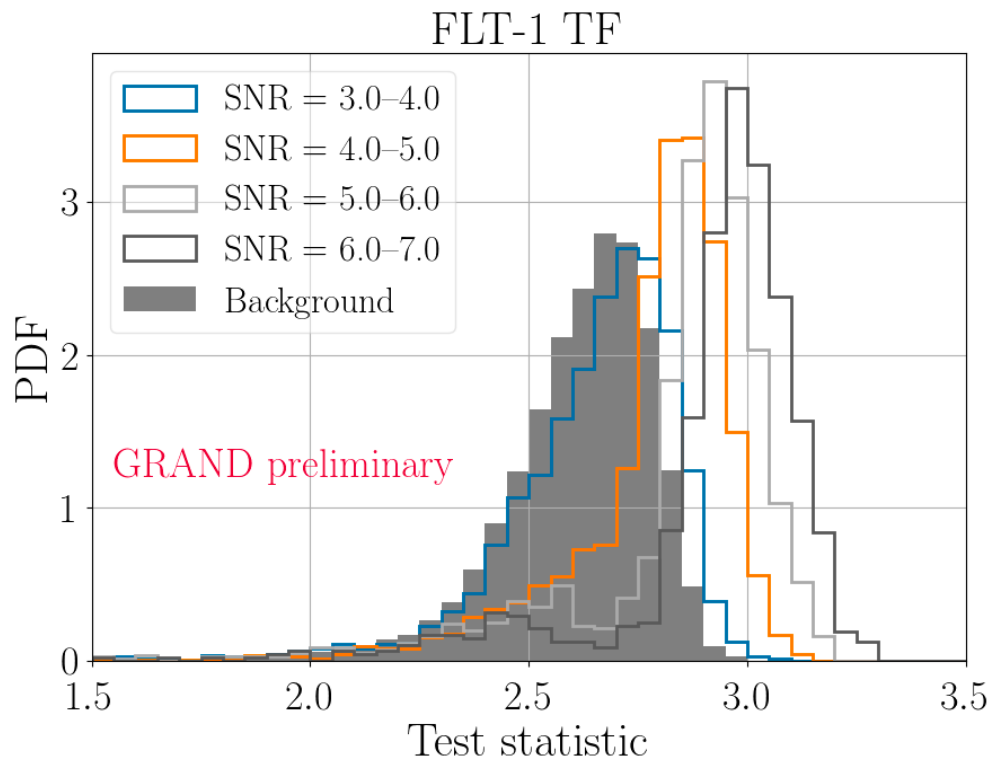


# Offline FLT-1 Performance

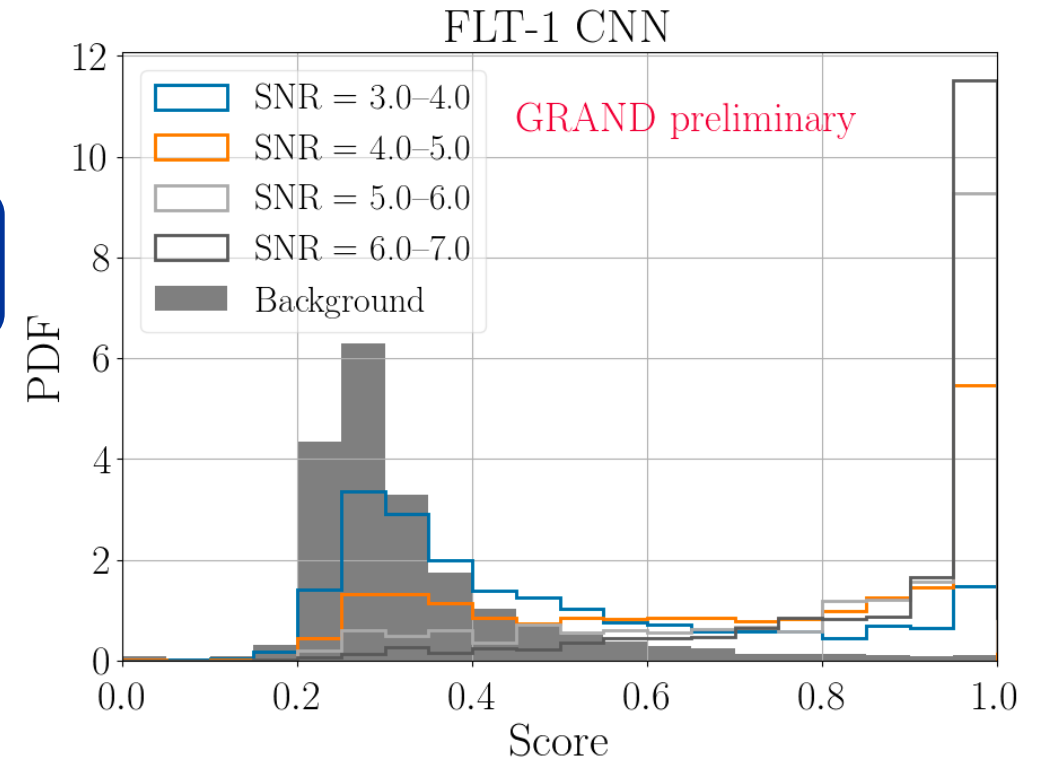
**Results**  
Testing data samples  
2 x 10,000 traces



- ▶ CNN has better **signal-background (S-B) separation**
- ▶ Template fitting (TF) still in **early stages!**

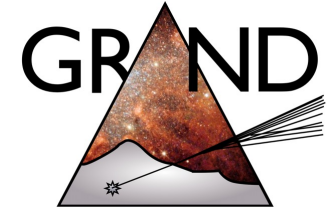


**SNR**  
Max. shower pulse  
/ noise RMS

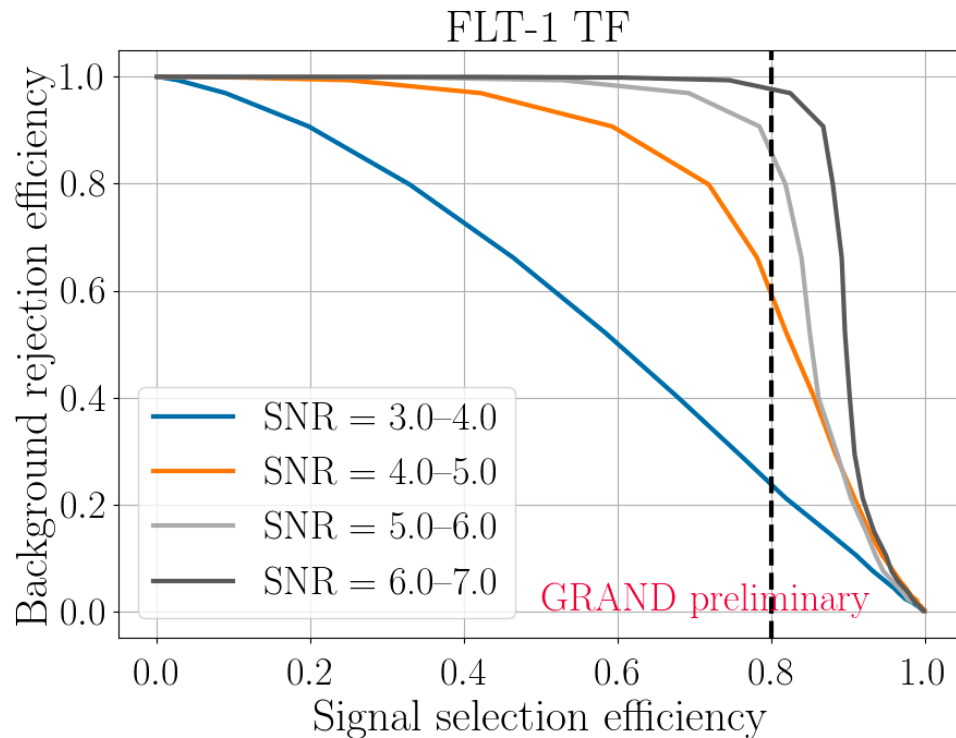


# Offline FLT-1 Performance

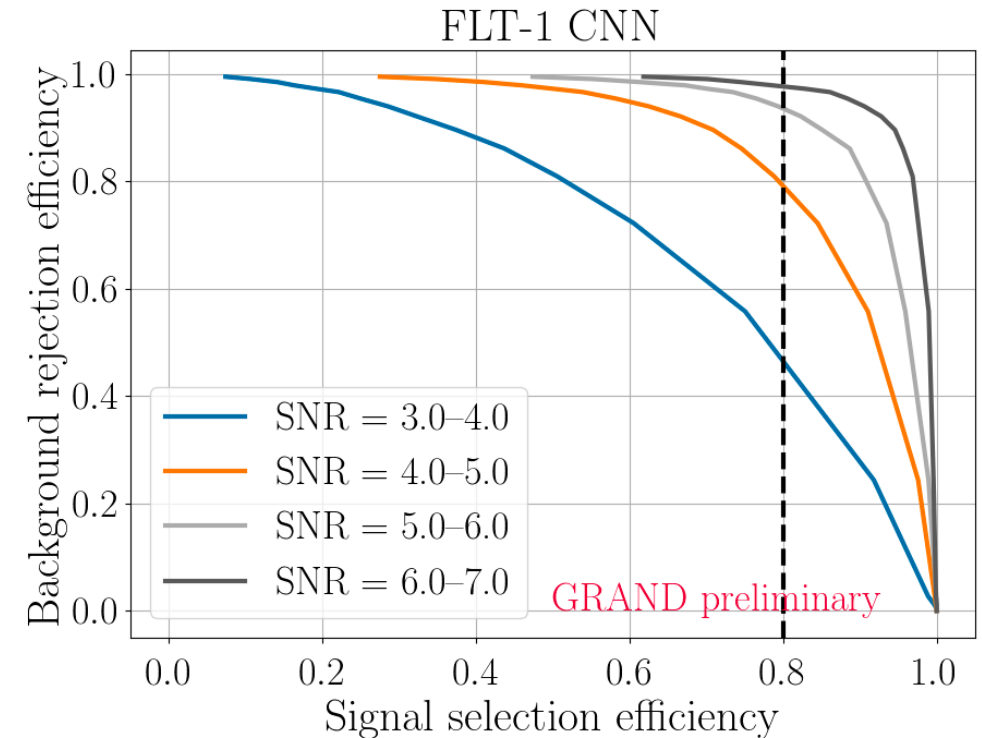
**Results**  
Testing data samples  
2 x 10,000 traces



- ▶ FLT-1 results looks **promising** for both methods
- ▶ If we **select 80% of signal at  $5\sigma$** , we can **reject 80-90% of background**



**SNR**  
Max. shower pulse  
/ noise RMS



# Conclusions and Outlook



## Summary

- ▶ Constructed **database** for NUTRIG
  - ▶ Background from **GP13 data**
  - ▶ Signal from **ZHAireS simulations**
- ▶ Considered two **FLT-1 algorithms**
  - ▶ **Template fitting** (PC)
  - ▶ **CNN** (J.M. Colley, S. Le Coz)
- ▶ Offline **FLT-1 results promising**
  - ▶ **CNN** currently better S-B separation than TF
  - ▶ **80–90% B rejection for 80% S selection @ $5\sigma$**

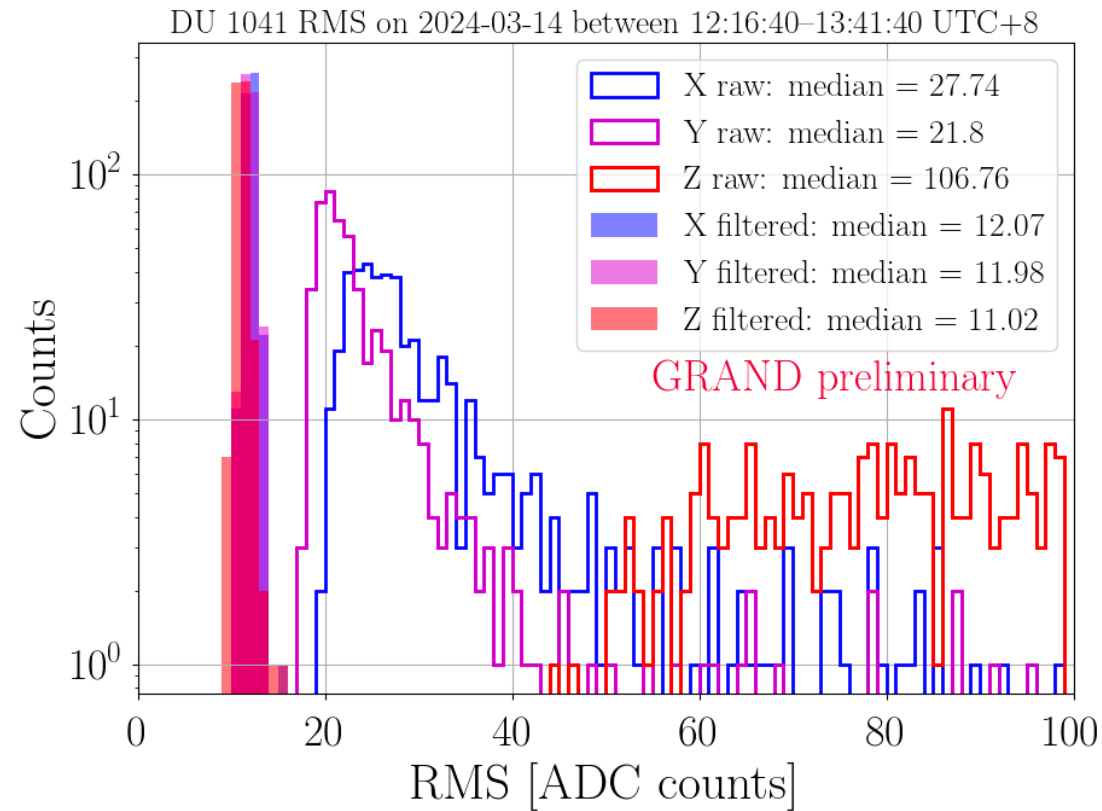
## Outlook

- ▶ **Optimize** FLT-1 algorithms
  - ▶ Reduce templates, **computation time**,...
- ▶ Perform **online tests** of FLT-1 methods
  - ▶ **Port** to CPU on front-end board
  - ▶ Controlled tests at **LPNHE test bench**
- ▶ Test FLT-1 at **GRAND@Nançay**
  - ▶ **Dedicated prototype** for NUTRIG
  - ▶ Tests in **realistic conditions** [[PC PoS ICRC2023 990](#)]

# BACKUP



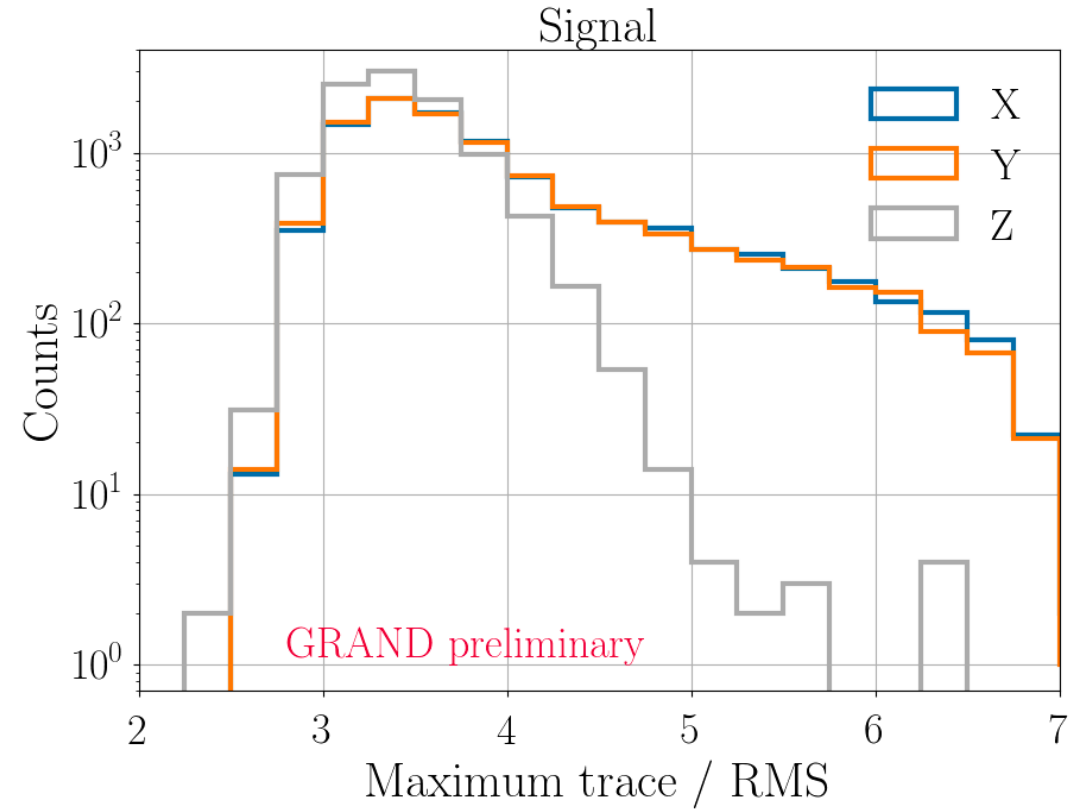
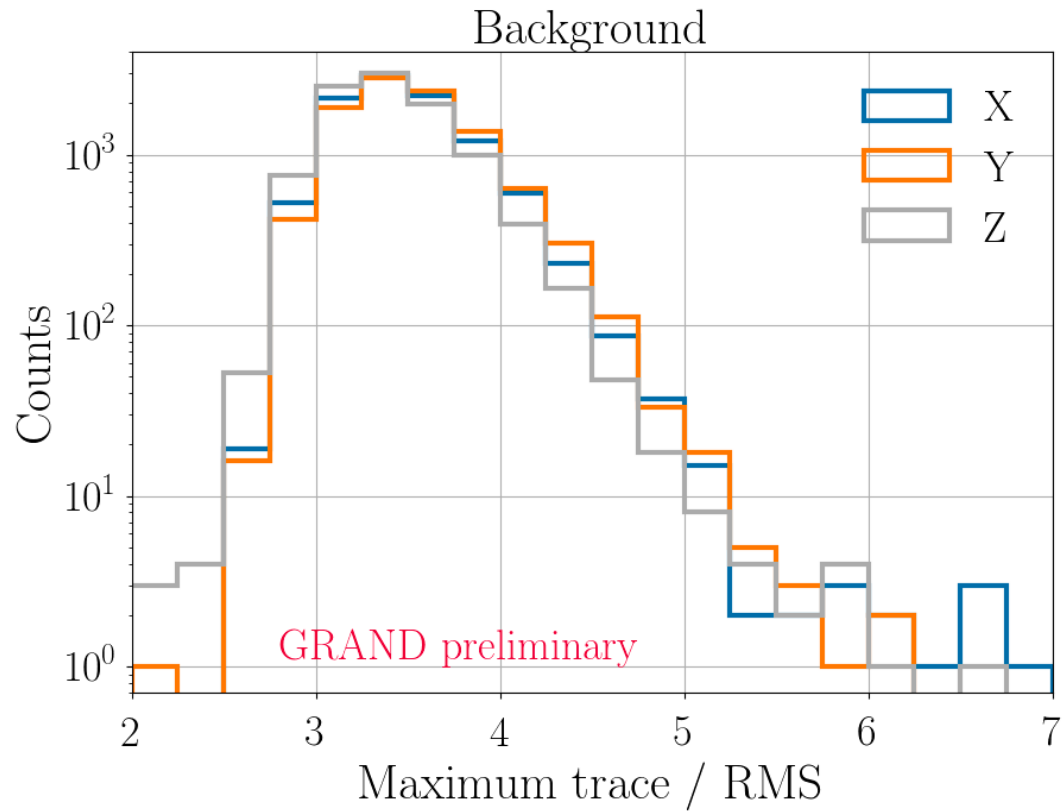
# Effect of Filters on RMS @ GP13



# Database Properties

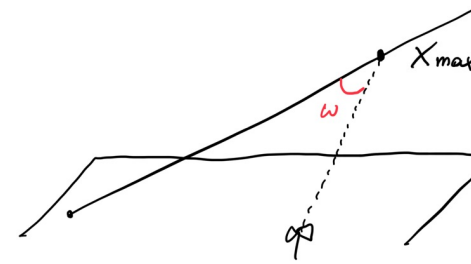
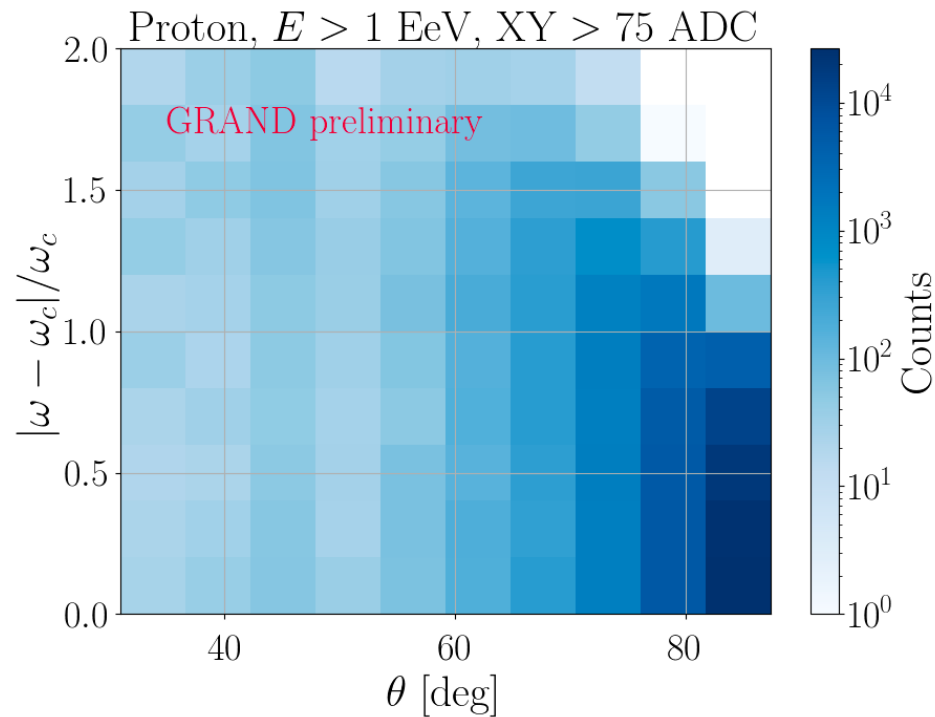


## Training samples

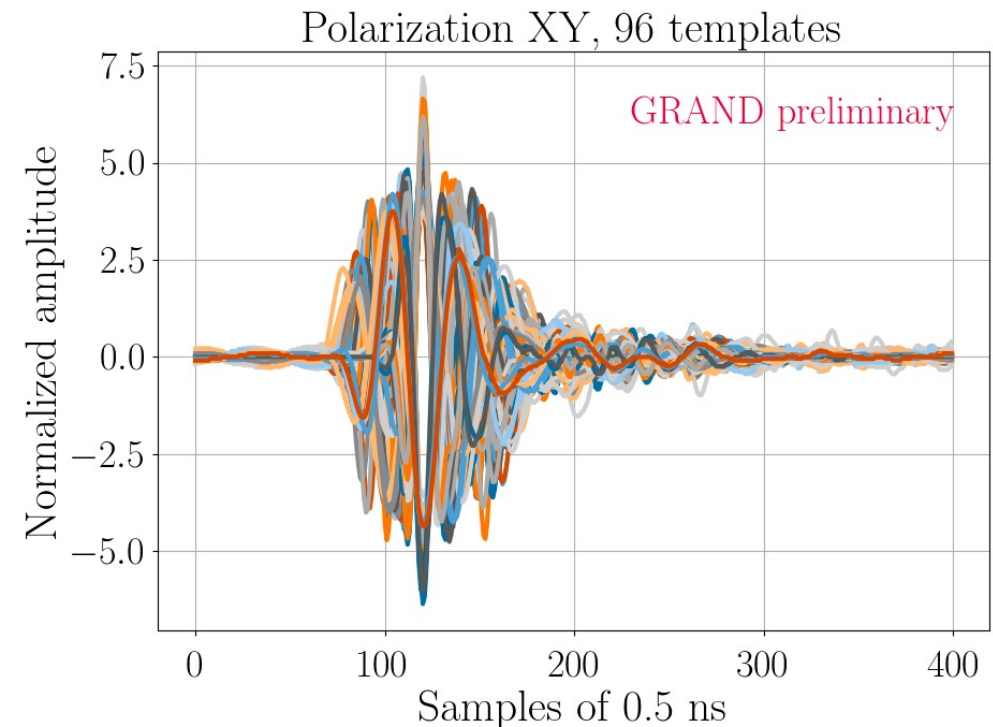


# Template FLT-1: Library

- ▶ Same **air-shower simulations** as DB
  - ▶ Keep **0.5 ns sampling**
  - ▶ Focus on  $E > 1 \text{ EeV}$
  - ▶ **Bin** air-shower pulses in  $\theta$  and  $\omega$



- ▶ **Randomly pick** one template per bin
  - ▶ **96 templates** for X+Y
  - ▶ 96 templates for Z (not considered in this work)





# Template FLT-1: Algorithm



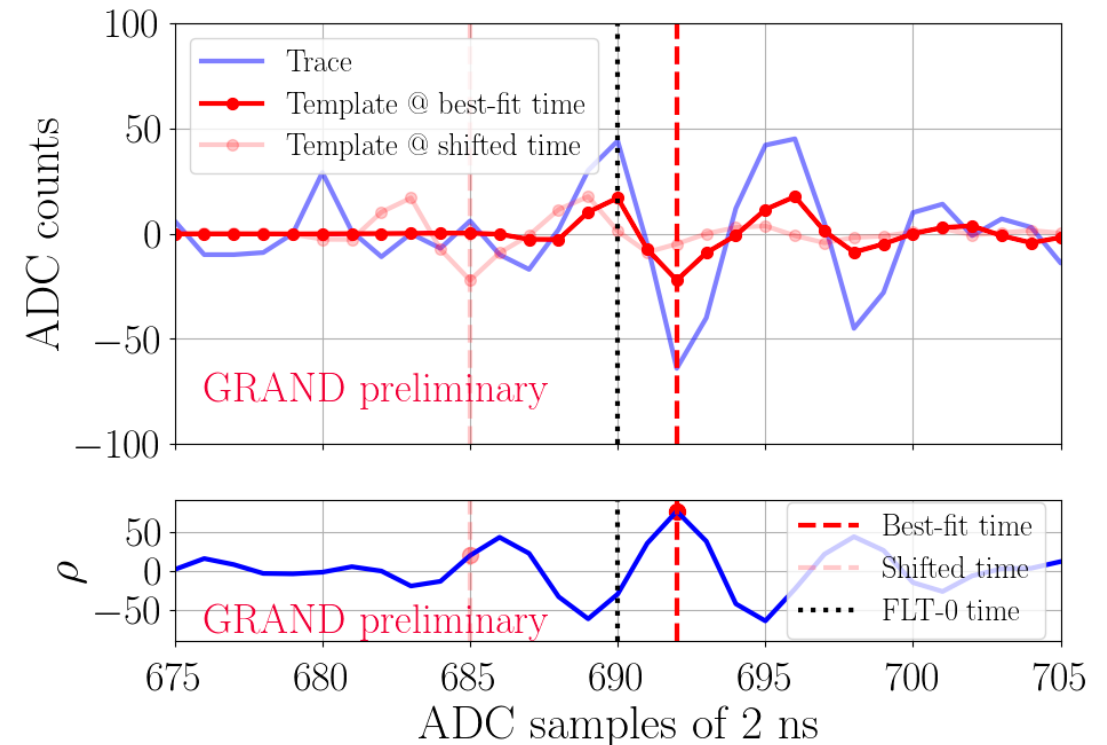
## Step 1: Fit template time

- ▶ Take **scan window** around FLT-0 time  $t_0$ 
  - ▶  $\tau \in [t_0 - 15 \text{ ADC samples}, t_0 + 15 \text{ ADC samples}]$
- ▶ Compute template-trace **cross correlation** for each time in window [\[Henrichs+ PoS ICRC2023 259\]](#)

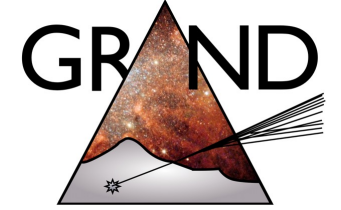
$$\rho_T(\tau) = \int T(t) V(t + \tau) dt$$

- ▶ **Maximum correlation** yields “best-fit” time

$$\hat{t}_{FLT} = \operatorname{argmax} |\rho_T(\tau)|$$



# Template FLT-1: Algorithm

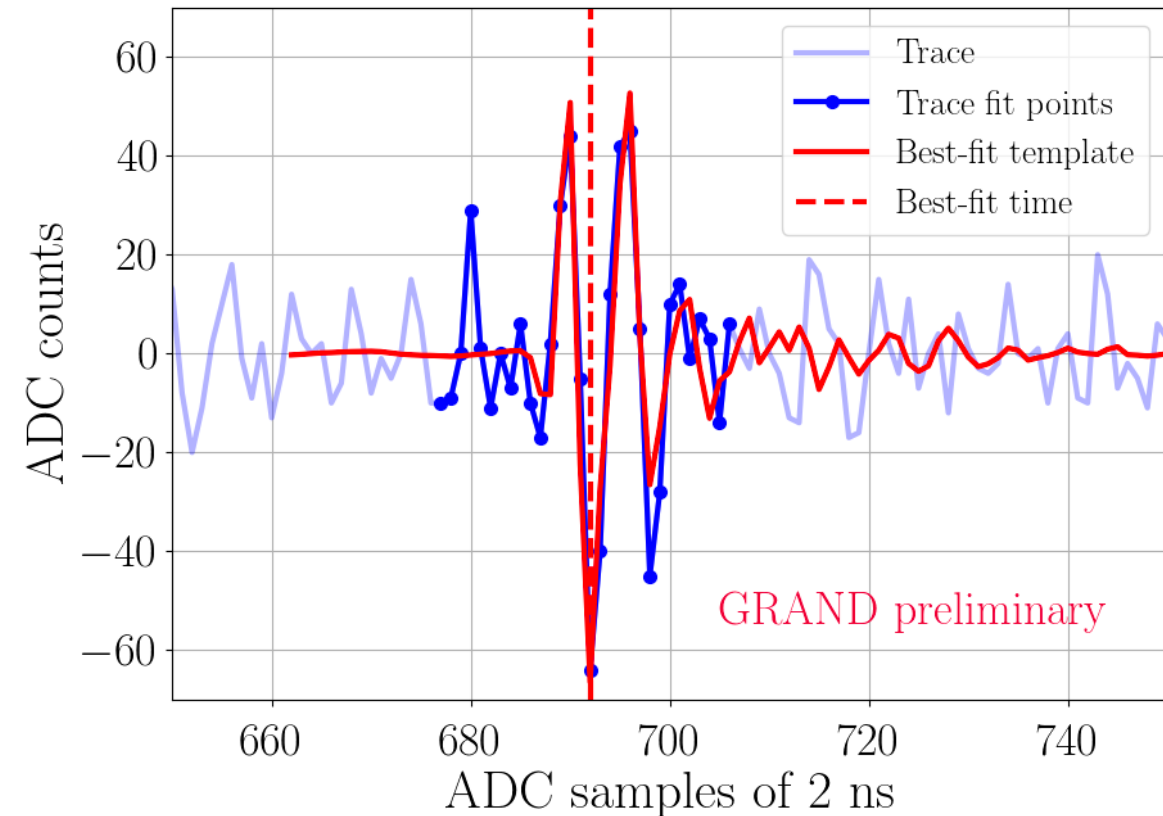


## Step 2: Fit template amplitude

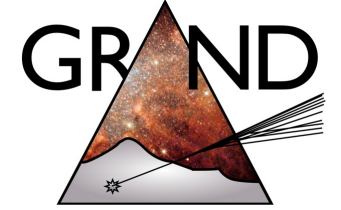
- ▶ Take **fit window** around best-fit time  $\hat{t}_{FLT}$ 
  - ▶  $t_i \in [\hat{t}_{FLT} - 10 \text{ ADC samples}, \hat{t}_{FLT} + 15 \text{ ADC samples}]$
- ▶ **Weight** fit points with  $\sigma_i = \text{RMS}^2 / V(t_i)$
- ▶ Perform a **least-squares fit**

$$\chi_T^2 = \min_{\kappa_T} \sum_i \frac{|V(t_i) - \kappa_T T(t_i)|^2}{\sigma_i^2}$$

- ▶ **Minimum**  $\chi_T^2$  yields best-fit amplitude  $\hat{\kappa}_T$



# Template FLT-1: Algorithm



## Step 3: Compute test statistic

► **Repeat** steps 1 & 2 for all templates

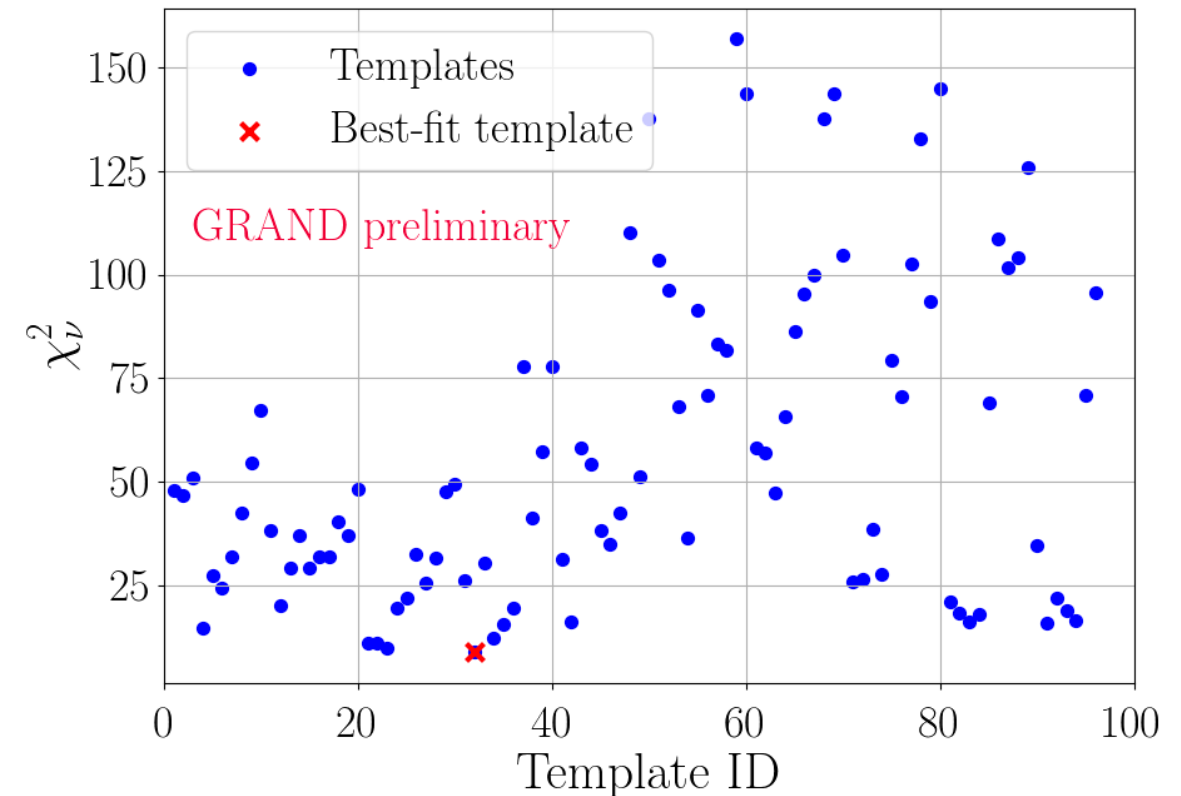
► Find the **best-fit template**

$$T_b = \operatorname{argmin}_T \chi_T^2$$

► Compute a **test statistic** as

$$\text{TS} = \log_{10} |\hat{\kappa}_b \rho_{T_b}(\hat{t}_{s,b})|$$

► **TS threshold** defines FLT-1 pass condition



# FLT-1 Selection Efficiency

